## <u>Avia LiDAR Sensor – Livox</u>

## **Basic Specs**

Model	AVIA
Laser Wavelength	905 nm
Laser Safety	Class 1 (IEC60825-1:2014)(Eye Safety)
Detection Range (@ 100	190 m @ 10% reflectivity
klx)	230 m @ 20% reflectivity
	320 m @ 80% reflectivity
Detection Range (@ 0 klx)	190 m @ 10% reflectivity
	260 m @ 20% reflectivity
	450 m @ 80% reflectivity
FOV	Non-repetitve scanning pattern:
	70.4° (Horizontal) ×77.2° (Vertical)
	Repetitve line scanning:
	70.4° (Horizontal) ×4.5° (Vertical)
Range Precision (1σ @	2 cm <sup>1</sup>
20m)	
Angular Precision (1σ)	< 0.05°
Beam Divergence	0.28° (Vertical) × 0.03° (Horizontal)
Point Rate	240,000 points/s (first or strongest return)
	480,000 points/s (dual return)
	720,000 points/s (triple return)
Data Latency	≤ 2 ms
Data Port	100 Mbps Ethernet
Data synchronization: (PPS+UTC)	IEEE 1588-2008 (PTPv2), PPS (Pulse Per Second), GPS
False Alarm Rate (@ 100 klx) <sup>2</sup>	< 0.0003%
IMU	Built-in model: BMI088
Operating Temperature	-4°F to 149°F (-20°C to 65°C)
IP Rating <sup>3</sup>	IP67
Power <sup>4</sup>	Repetitive scanning pattern: 9 W (Startup: 16W)
	Non-repetitive: 8 W (Startup: 16W)
Power Supply Voltage	10 ~ 15 V DC(with Converter 2.0: 9~30V DC)
Range <sup>5</sup>	
Noise	40cm omnidirectional <45 dBA
Dimensions	91×61.2×64.8 mm

M	400 ( ):  ( )   ( )
Weight	498 g (without cables)

## Notes

- 1. Measured in an environment of 25°C with a target (80% reflectivity) 20 meters away. The result may vary under different test conditions.
- 2. The false alarms ratio of the noise created by the stray light in a test environment of 0 to 100 klx at a temperature of  $25^{\circ}$ C.
- 3. The Livox Avia has an overall IP rating of IP67 (not including Livox Converter 2.0 and cables)
- 4. Starting power, especially at low temperature, might be significantly larger than the typical power. Please refer to user manuals for detailed information.
- 5. Make sure the output voltage of the power supply is within this range at all times.