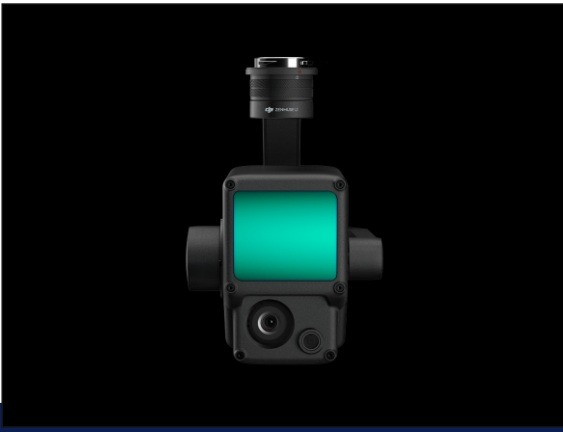




**dji**

**Zenmuse**  
**L1**



# General

<b>Product Name</b>	Zenmuse L1
<b>Dimensions</b>	152×110×169 mm
<b>Weight</b>	930±10 g
<b>Power</b>	Typical: 30 W; Max: 60 W
<b>IP Rating</b>	Ip54
<b>Supported Aircraft</b>	Matrice 300 RTK
<b>Operating Temperature Range</b>	-20° to 50° C (-4° to 122° F) 0° to 50° C (32° to 122° F) (when using RGB mapping camera)
<b>Storage Temperature Range</b>	-20° to 60° C (-4° to 140° F)

# System Performance

<b>Detection Range</b>	450 m @ 80% reflectivity, 0 klx ; 190 m @ 10% reflectivity, 100 klx
<b>Point Rate</b>	Single return: max. 240,000 pts/s ; Multiple return: max. 480,000 pts/s
<b>System Accuracy (RMS 1σ)</b>	Horizontal: 10 cm @ 50 m; Vertical: 5 cm @ 50 m
<b>Real-time Point Cloud Coloring Modes</b>	Reflectivity, Height, Distance, RGB



DJI Zenmuse L1 LIDAR Workflow



# Lidar

<b>Ranging Accuracy (RMS 1σ)<sup>2</sup></b>	3 cm @ 100 m
<b>Maximum Returns Supporte</b>	3
<b>Scan Modes</b>	Non-repetitive scanning pattern, Repetitive scanning pattern
<b>Laser Safety</b>	Class 1 (IEC 60825-1:2014) (Eye Safety)
<b>FOV</b>	Non-repetitive scanning pattern: 70.4° (horizontal) × 77.2° (vertical) ; Repetitive scanning pattern: 70.4° (horizontal) × 4.5° (vertical)

# Inertial Navigation System

<b>IMU Update Frequency</b>	200 Hz
<b>Accelerometer Range</b>	±8 g
<b>Angular Velocity Meter Range</b>	±2000 dps
<b>Yaw Accuracy ( RMS 1σ )</b>	Real-time: 0.3°, Post-processing: 0.15°
<b>Pitch / Roll Accuracy ( RMS 1σ )</b>	Real-time: 0.05°, Post-processing: 0.025°

# Auxiliary Positioning Vision Sensor

<b>Resolution</b>	1280×960
<b>FOV</b>	95°



# RGB Mapping Camera

<b>Sensor Size</b>	1 inch
<b>Effective Pixels</b>	20 MP
<b>Photo Size</b>	5472×3078 (16:9); 4864×3648 (4:3); 5472×3648 (3:2)
<b>Focal Length</b>	8.8 mm / 24 mm (Equivalent)
<b>Shutter Speed</b>	Mechanical Shutter Speed: 1/2000 - 8 s Electronic Shutter Speed: 1/8000 - 8 s
<b>ISO</b>	Video: 100 – 3200 (Auto), 100 – 6400 (Manual) Photo: 100 - 3200 (Auto), 100 - 12800 (Manual)
<b>Aperture Range</b>	f/2.8 - f/11
<b>Supported File System</b>	FAT (≤32 GB); exFAT (>32 GB)
<b>Photo Format</b>	JPEG
<b>Video Format</b>	MOV, Mp4
<b>Video Resolution</b>	H.264, 4K: 3840×2160 30p

## Gimbal

<b>Stabilized System</b>	3-axis (tilt, roll, pan)
<b>Angular Vibration Range</b>	0.01°
<b>Mount</b>	Detachable DJI SKYPORT
<b>Mechanical Range</b>	Tilt: -120° to +30°; Pan: ±320°
<b>Operation Modes</b>	Follow/Free/Re-center



## Data Storage

<b>Raw Data Storage</b>	Photo/IMU/Point cloud data storage/GNSS/Calibration files
<b>Supported microSD Cards</b>	microSD: Sequential writing speed 50 MB/s or above and UHS-I Speed Grade 3 rating or above; Max capacity: 256 GB
<b>Recommended microSD Cards</b>	SanDisk Extreme 128GB UHS-I Speed Grade 3 SanDisk Extreme 64GB UHS-I Speed Grade 3 SanDisk Extreme 32GB UHS-I Speed Grade 3 SanDisk Extreme 16GB UHS-I Speed Grade 3 Lexar 1066x 128GB U3 Samsung EVO Plus 128GB

## Post-processing Software

<b>Supported Software</b>	DJI Terra
<b>Data Format</b>	DJI Terra supports exporting standard format point cloud models: Point cloud format: PNTS/LAS/PLY/PCD/S3MB format

1. The accuracy was measured under the following conditions in a DJI laboratory environment: after a 5-minute warm up, using Mapping Mission with Calibration Flight enabled in DJI Pilot, and with the RTK in FIX status. The relative altitude was set to 50 m, flight speed to 10 m/s, gimbal pitch to  $-90^{\circ}$ , and each straight segment of the flight route was less than 1000 m. DJI Terra was used for post-processing.
2. Measured in an environment of  $25^{\circ}\text{C}$  with a target (80% reflectivity) 100 meters away. The result may vary under different test conditions.
3. The recommended microSD cards may be updated in future. Visit the DJI official website for the latest information.

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